



## SKILLS

### **Programming & ML:**

Python, PyTorch, Numpy, Pandas, OpenCV

### **Computer Vision & 3D Perception:**

Object Detection, Point Cloud Segmentation, 3D Scene understanding, Occupancy Networks

### **Model Development & Evaluation:**

Model Training, Benchmarking, Dataset Curation, Performance Analysis

### **Tools & Platforms:**

Linux, Git, Docker, ROS, CARLA

## PROJECTS

### **VLM Optimization for Traffic**

#### **Light/Sign Recognition in AD**

- Optimized Vision-Language Models for traffic light and sign recognition in autonomous scenarios
- Improved recognition accuracy by 15% and validated decision-making performance using simulation-based testing in CARLA

### **Visual-Inertial SLAM using OPENVINS**

- Developed and evaluated a Visual-Inertial Odometry pipeline on 1:10 Autonomous Vehicle using camera and IMU data in ROS environment
- Worked on feature tracking, sensor synchronization, and state estimation for robust pose state

### **Camera based Localization & Tracking**

- Implemented a real-time vision-based localization and tracking pipeline using monocular camera input, focusing on robustness perception under various lighting
- Integrated YOLO based detection system to support perception validation across multiple scenes

### **KITTI-based Object Detection System**

#### **for Road Safety**

- Developed and trained a YOLOv8-object detection system on KITTI dataset
- Built an inference and visualization pipeline to evaluate model performance and reliability

## LANGUAGES

- Deutsch: B1
- English: C1

## PROFILE

AI Research Engineer with hands-on experience developing and evaluating computer vision models for 3D perception and autonomous systems. Worked on projects involving object detection, tracking, visual-inertial SLAM, and simulation-based benchmarking, with a strong interest in robust, real-world AI systems.

## EXPERIENCE

### **Master Thesis Student – Daimler Truck AG, Stuttgart**

**Title: Ground Truth Generation for Voxel-Based 3D Occupancy Prediction using Multi-LiDAR Truck Data** Feb. 2025 – Aug. 2025

- Built a pipeline to generate dense 3D occupancy ground truth labels for training vision-based prediction models on a truck-specific dataset.
- Reduced manual annotation costs by **80%** through point cloud segmentation and voxel densification on the fused LiDAR point clouds.
- Designed and evaluated scalable data pipelines supporting perception model training and validation.

### **Student Assistant – Institute for Intelligent Systems, Esslingen**

#### **Research Assistant**

Aug. 2024 – Aug. 2025

- Trained and evaluated Vision-Language Models (VLMs) for proper instruction following of autonomous vehicles, conducted simulation-based validation, and analysed performance in CARLA to support autonomous behaviour.
- Achieved **15%** higher driving scores via enhanced traffic light/sign recognition.
- Conducted literature reviews, designed experiments, and analysed results to guide model development and evaluation.

### **HCL Engineering and R&D Services, Bangalore, India**

#### **Engineer for Design and Simulation**

Aug. 2021 – Apr. 2023

- Design and Simulation of COWL Anti-ice valves and their components for aircraft. Creation of Manufacturing drawings based on GD&T principles.
- Conducted quality checks and managed the release of finalized drawings to the customer, ensuring all the deliverables were accurate and on schedule.

### **Team Torpedo, SAE BAJA INDIA ATV Design, Coimbatore, India**

#### **Vice-Captain, Amrita Vishwa Vidyapeetham.**

May 2018 – July 2021

- Design and Simulation of Vehicle Dynamics for All Terrain Vehicle.
- Collaboration on the full-cycle development of the vehicle, from initial design, through to physical fabrication, assembly, and performance testing.

## EDUCATION

### **Hochschule Esslingen, Germany**

#### **Master of Engineering, Automotive Systems**

Sept. 2023 – Aug. 2025

- Specialization in autonomous systems with emphasis on Computer Vision and Deep Learning.
- Hands-on experience in perception algorithms, sensor fusion, dataset handling, and adaptation for autonomous driving tasks

### **Amrita Vishwa Vidyapeetham, Coimbatore, India**

#### **Bachelor of Technology, Mechanical Engineering**

July 2017 – Aug. 2021

- Specialization in Automotive Engineering with emphasis on vehicle dynamics design, powertrain systems, and chassis design.
- Application of Mechanical Systems to Modern Automotive Technologies.